



LECTURE 30

Sorting: Elementary Algorithms

CSC211 · Algorithms and Data Structures

Agenda

1 The sorting problem, and what characterizes a sorting algorithm

2 Bubble sort, selection sort, and insertion sort

3 Tracing each algorithm pass by pass

4 In-place sorting, and proving bubble sort's $O(n)$ best case

5 A head-to-head comparison/swap count across all three

6 A direct comparison of all three algorithms

The Sorting Problem

- Sorting rearranges a collection into a defined order, using two core operations: comparing and swapping (or shifting).

1

Time complexity

How comparisons/swaps grow with n .

2

Space complexity

Extra memory beyond the input array.

3

Stability

Do equal elements keep their relative order?

4

In-place

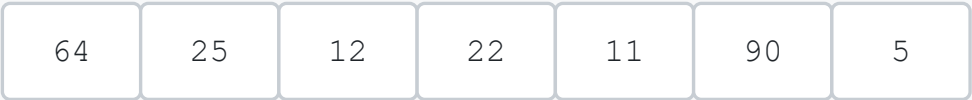
Sorts within the original array, or needs a copy?

ALGORITHM 1

Bubble Sort

- Repeatedly steps through the array, swapping adjacent elements that are in the wrong order — each pass "bubbles" the largest remaining value to the end.

Original

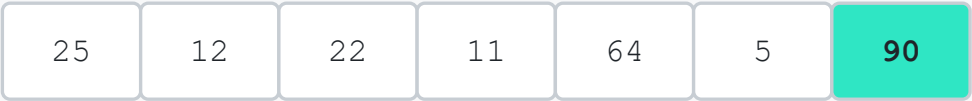


Compare 64,25 → swap



Adjacent out-of-order pair gets swapped.

End of pass 1: 90 bubbled to the end



Largest remaining value reaches its final position.

A "swapped" flag lets the algorithm stop the instant a full pass makes zero swaps — giving bubble sort a best case of $O(n)$.

Bubble Sort — Code

`elementary_sorts.cpp`

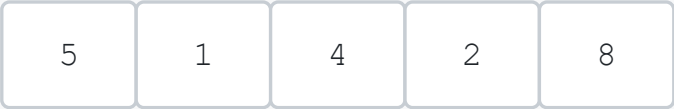
```
for (int pass = 0; pass < n - 1; pass++) {  
    bool swapped = false;  
    for (int i = 0; i < n - 1 - pass; i++) {  
        if (arr[i] > arr[i + 1]) {  
            swap(arr[i], arr[i + 1]);  
            swapped = true;  
        }  
    }  
    if (!swapped) break; // already sorted  
}
```

- Inner loop shrinks by one each pass ($n-1$ -pass) — the sorted tail never needs re-checking.
- The swapped flag triggers early exit on nearly-sorted input.
- All swaps are adjacent — the algorithm never looks more than one position ahead.

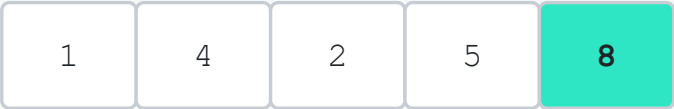
5-ELEMENT ARRAY: 5 1 4 2 8

Tracing Bubble Sort Pass by Pass

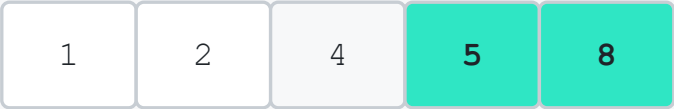
Initial



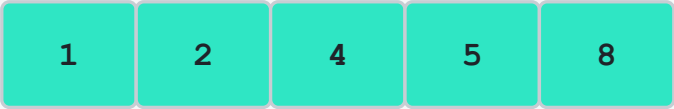
After pass 1



After pass 2



After pass 3 (no swaps — stop early)



Only 3 passes ran on a 5-element array, not the full $n-1=4$ the outer loop allows — confirming the early-exit optimization triggers in practice.

Proving the Best Case with Real Counts

999

comparisons, 0 swaps — ALREADY-SORTED input (n=1000)

499,500

comparisons, 499,500 swaps — REVERSE-SORTED input

- 999 comparisons is exactly $n-1$ — one full pass, confirming the best case directly, not just in theory.
- $499,500 = 999 \times 1000 / 2$, exactly the $n(n-1)/2$ the $O(n^2)$ bound predicts for a pass that never exits early.
- Same size input (n=1000), differing only in starting order — almost a 500x gap in comparisons.

ALGORITHM 2

Selection Sort

- Finds the MINIMUM of the remaining unsorted portion and swaps it directly into place — exactly one swap per outer-loop pass.

Scan all 5, find min = 11

Swap into position 0

Scan remaining 4, find min = 12

Swap into position 1



Every round does the SAME amount of scanning regardless of how the data started — selection sort has no best-case advantage: best, average, and worst case are all $O(n^2)$.

Selection Sort — Code

`elementary_sorts.cpp`

```
for (int i = 0; i < n - 1; i++) {  
    int minIndex = i;  
    for (int j = i + 1; j < n; j++) {  
        if (arr[j] < arr[minIndex])  
            minIndex = j;  
    }  
    swap(arr[i], arr[minIndex]);  
}
```

- Inner loop always scans the entire remaining unsorted region — no early exit possible.
- Exactly one `swap()` call per outer-loop iteration: $n-1$ swaps total, always.
- Swap count is far lower than bubble sort's, at the cost of always doing the full scan.

ALGORITHM 3

Insertion Sort

- Builds the sorted portion one element at a time: each new element shifts backward through the sorted portion until it reaches its spot.



Each already-sorted element only shifts as far as it needs to — like bubble sort, best case $O(n)$ on already-sorted input (the inner while loop never runs).

Insertion Sort — Code

`elementary_sorts.cpp`

```
for (int i = 1; i < n; i++) {  
    int key = arr[i];  
    int j = i - 1;  
    while (j >= 0 && arr[j] > key) {  
        arr[j + 1] = arr[j]; // shift right  
        j--;  
    }  
    arr[j + 1] = key; // insert key  
}
```

- The while loop shifts, not swaps — one comparison-driven pass moves the key directly to its spot.
- On already-sorted input the while condition is false immediately: $O(n)$ best case.
- Real hybrid library sorts (Lecture 31) fall back to insertion sort for small sub-arrays.

A SHARED ADVANTAGE

In-Place Sorting

- All three algorithms rearrange the array's own elements using only a small, constant amount of extra memory (a few loop variables) — never a second array the size of the input.

Bubble Sort

$O(1)$

extra space

Selection Sort

$O(1)$

extra space

Insertion Sort

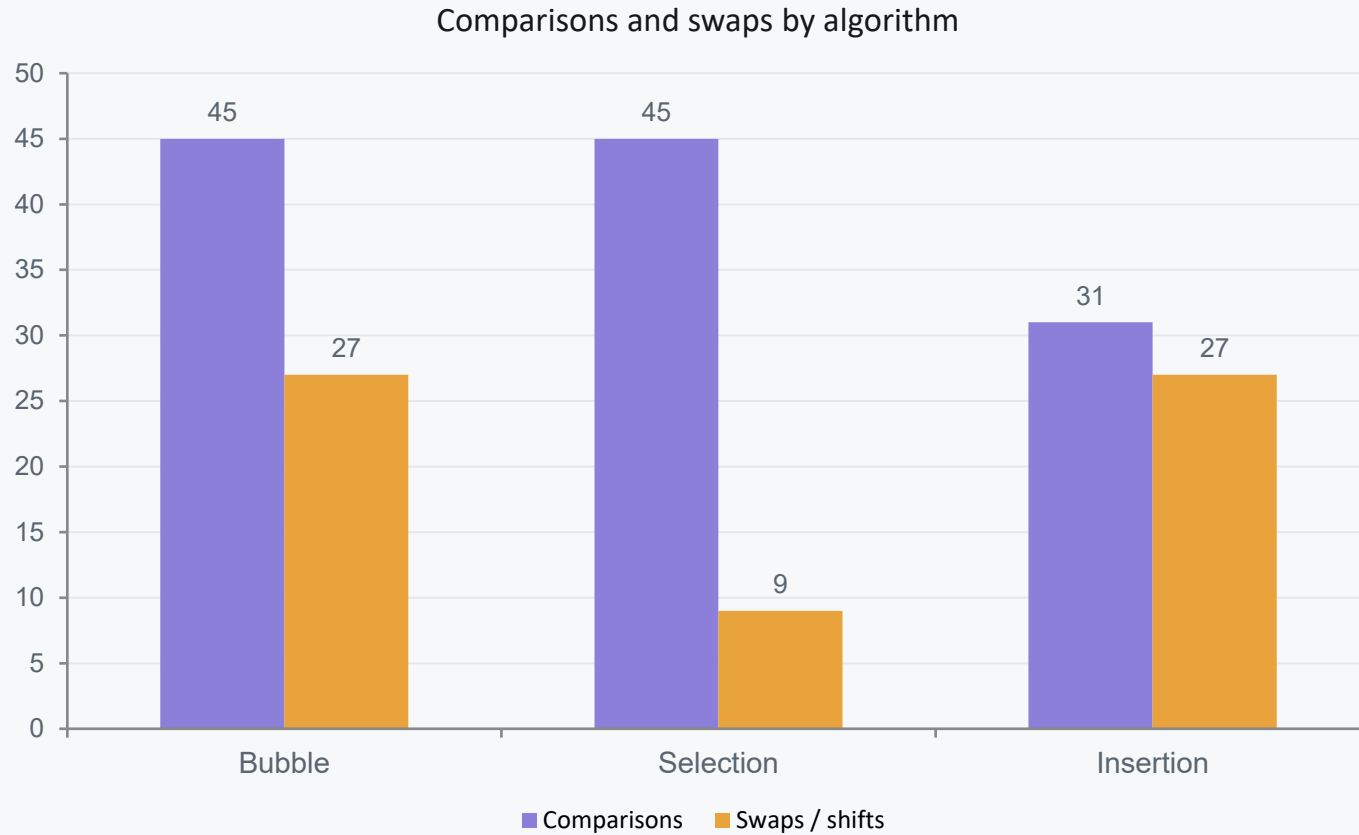
$O(1)$

extra space

A real advantage they share, despite their $O(n^2)$ time complexity.

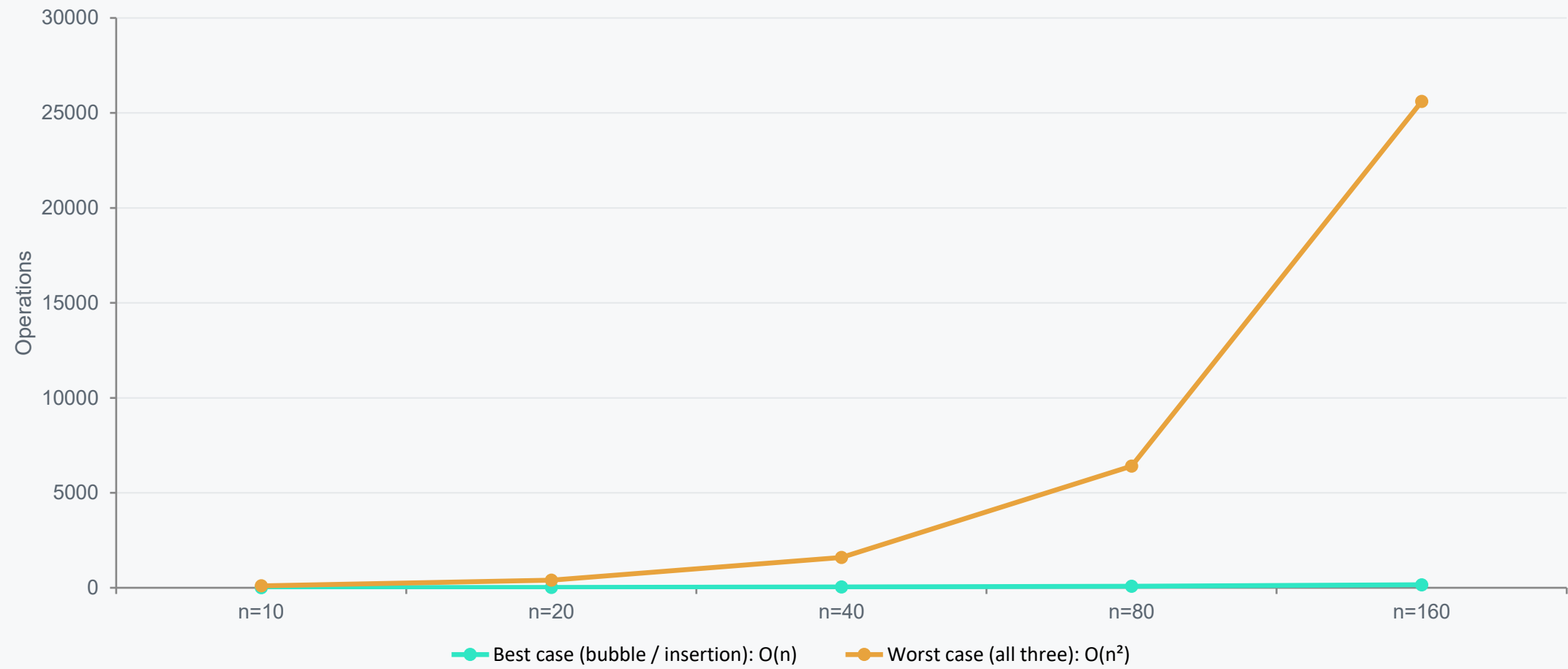
SAME 10-ELEMENT INPUT: 64 25 12 22 11 90 5 34 77 3

A Head-to-Head Count



- Bubble and selection both make 45 comparisons here — $n(n-1)/2$ for $n=10$.
- Selection's swaps ($9 = n-1$) are far lower than bubble's (27) — it always does minimal swaps.
- Insertion needed the fewest comparisons (31) — evidence it's generally preferred in practice.

Big-O Growth: $O(n)$ vs. $O(n^2)$



Comparison of Elementary Sorts

	Best	Average	Worst	Space	Stable?
Bubble Sort	$O(n)$	$O(n^2)$	$O(n^2)$	$O(1)$	Yes
Selection Sort	$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(1)$	No
Insertion Sort	$O(n)$	$O(n^2)$	$O(n^2)$	$O(1)$	Yes

Despite sharing the same worst-case complexity, insertion sort is generally preferred in practice — same best-case advantage as bubble sort, but does noticeably less work on average.



CLOSING

Key Takeaways

- Bubble sort's early-exit "swapped" flag gives it $O(n)$ best case — confirmed with 999 comparisons, 0 swaps on 1,000 sorted elements.
- Selection sort always scans the full remaining region — $O(n^2)$ in every case, with no benefit from partially-sorted input.
- Insertion sort builds a sorted portion incrementally — $O(n)$ best case and generally the most efficient of the three in practice.
- Tracing an algorithm pass by pass turns an abstract " $O(n)$ best case" claim into something you can actually see happen.
- All three are $O(1)$ extra space (in-place), but all three are $O(n^2)$ worst case — Lecture 31 covers algorithms that do better.